

HOMWORK # 5

SOLUTIONS

(1)

(PREPARED BY KARTIK)

(1) EXERCISE 7.5
Page 384, 37

Solve $ty'' - 2y' + ty = 0$

with $y(0) = 1$ and $y'(0) = 0$

$$\mathcal{L}\{ty''\} - 2\mathcal{L}\{y'\} + \mathcal{L}\{ty\} = 0$$

$$-\frac{d}{ds}(s^2 Y(s) - sy(0) - y'(0)) - 2(sY(s) - y(0)) - (1) \frac{d}{ds} Y(s) = 0$$

where $\mathcal{L}\{y(t)\} = Y(s)$

Substituting the initial value conditions
we get

$$-\frac{d}{ds}(s^2 Y(s) - s) - 2(sY(s) - 1)$$

$$-\frac{d}{ds} Y(s) = 0$$

$$\therefore -(2sY(s) + s^2 Y'(s) - 1) - 2(sY(s) - 1)$$

$$-Y'(s) = 0$$

$$\therefore - (2s Y(s) + s^2 Y'(s) - 1) - 2(s Y(s) - 1) - Y'(s) = 0$$

$$\therefore - (s^2 + 1) Y'(s) - 4s Y(s) + 3 = 0$$

$$\therefore (s^2 + 1) Y'(s) + 4s Y(s) = 3$$

$$\therefore \boxed{Y'(s) + \frac{4s}{(s^2+1)} Y(s) = \frac{3}{(s^2+1)}}$$

This is a linear first order differential equation with Y (dep var) and s

use discussion (ind var).

in Sec 2-3 to solve equation

$$(1) \mu(s) = e^{\int \frac{4s}{(s^2+1)} ds}$$

$$= e^{2 \log |s^2+1|}$$

$$= e^{\log (s^2+1)^2}$$

$$= (s^2+1)^2$$

$$\boxed{\begin{aligned} \int \frac{4s}{(s^2+1)} ds \\ \text{Let } s^2+1 = t \\ 2s ds = dt \\ \int \frac{2dt}{t} = 2 \log t \\ = 2 \log |s^2+1| \end{aligned}}$$

$$(2) Y(s) = \frac{1}{\mu(s)} \left[\int \mu(s) \frac{3}{(s^2+1)} ds + C \right]$$

$$\therefore Y(s) = \frac{1}{(s^2+1)^2} \left[\int (s^2+1)^2 \frac{3}{(s^2+1)} ds + C \right]$$

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$$\therefore Y(s) = \frac{1}{(s^2+1)^2} \left[\int 3(s^2+1) ds + C \right]$$

$$= \frac{1}{(s^2+1)^2} \left[\frac{3s^3}{3} + 3s + C \right]$$

$$Y(s) = \frac{s^3 + 3s}{(s^2+1)^2} + \frac{C}{(s^2+1)^2} \rightarrow \textcircled{\text{II}}$$

$$\therefore y(t) = L^{-1} \{ Y(s) \} = L^{-1} \left\{ \frac{(s^3+3s)}{(s^2+1)^2} + \frac{C}{(s^2+1)^2} \right\}$$

$$= L^{-1} \left\{ \frac{(s^3+3s)}{(s^2+1)^2} \right\} + C L^{-1} \left\{ \frac{1}{(s^2+1)^2} \right\}$$

(Since C is a constant)

Now

$$L^{-1} \left\{ \frac{(s^3+3s)}{(s^2+1)^2} \right\} = L^{-1} \left\{ \frac{As+B}{(s^2+1)} + \frac{Cs+D}{(s^2+1)^2} \right\}$$

$$= L^{-1} \left\{ \frac{(As+B)(s^2+1) + (Cs+D)}{(s^2+1)^2} \right\}$$

(4)

$$= L^{-1} \left\{ \frac{(As+B)(s^2+1) + (Cs+D)}{(s^2+1)^2} \right\}$$

$$= L^{-1} \left\{ \frac{As^3 + (A+C)s + Bs^2 + (B+D)}{(s^2+1)^2} \right\}$$

$$\therefore L^{-1} \left\{ \frac{s^3 + 3s}{(s^2+1)^2} \right\} = L^{-1} \left\{ \frac{As^3 + Bs^2 + (A+C)s + (B+D)}{(s^2+1)^2} \right\}$$

$$\therefore A=1 \quad A+C=3 \quad B=D=0$$

$$\therefore C=2$$

$$\therefore L^{-1} \left\{ \frac{s^3 + 3s}{(s^2+1)^2} \right\} = L^{-1} \left\{ \frac{s}{(s^2+1)} + \frac{2s}{(s^2+1)^2} \right\}$$

$$= \cos t + 2L^{-1} \left\{ \frac{s}{(s^2+1)^2} \right\}$$

Now $L^{-1} \left\{ \frac{s}{(s^2+1)^2} \right\} = L^{-1} \left\{ \frac{s}{(s^2+1)} \cdot \frac{1}{(s^2+1)} \right\}$

$$= \cos t * \sin t \quad = \int \cos(t-\omega) \sin(\omega) d\omega$$

(CONVOLUTION)

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$$\therefore \mathcal{L}^{-1} \left\{ \frac{s}{(s^2+1)^2} \right\} = \int_0^t \cos(t-u) \sin(u) du$$

$$\cos A \sin B = \frac{1}{2} \left[\sin(B+A) + \sin(B-A) \right]$$

$$\int_0^t \cos(t-u) \sin(u) du = \int_0^t \frac{1}{2} \left[\sin(t) + \sin(2u-t) \right] du$$

$$= \frac{1}{2} \left[\sin(t)u - \frac{\cos(2u-t)}{2} \right]_{u=0}^{u=t}$$

$$= \frac{1}{2} \left[t \sin t - \frac{1}{2} \cancel{\cos(t)} + \frac{\cancel{\cos(-t)}}{2} \right]$$

Since $\cos(-t) = \cos(t)$

$$= \frac{1}{2} t \sin t$$

$$\therefore \mathcal{L}^{-1} \left\{ \frac{s^3 + 3s}{(s^2+1)^2} \right\} = \cos t + \frac{2}{2} t \sin t$$

⑥

We will use the hint
to compute/write

$$\mathcal{L}^{-1} \left\{ \frac{1}{(s^2+1)^2} \right\} (t) = \frac{1}{2} (s \sin t - t \cos t)$$

$$y(t) = \cos t + \frac{2}{2} t \sin t + \frac{C}{2} (s \sin t - t \cos t)$$

$$= \cos t + t \sin t + \frac{C}{2} (s \sin t - t \cos t)$$

②

EXERCISE
7-6

Problem 19

Consider

$$I''(t) + 2I'(t) + 2I(t) = g(t)$$

$$I(0) = 10, \quad I'(0) = 0$$

$$\text{and } g(t) = \begin{cases} 20, & 0 < t < 3\pi \\ 0, & 3\pi < t < 4\pi \\ 20, & 4\pi < t \end{cases}$$

Determine $I(t)$.

Step 1:- Write $g(t)$ in terms of step functions

(7)

$$g(t) = 20 + (0-20)u(t-3\pi) + (20-0)u(t-4\pi)$$

$$= 20 - 20u(t-3\pi) + 20u(t-4\pi)$$

$$\therefore G(s) = \mathcal{L}\{g(t)\} = \frac{20}{s} - \frac{20e^{-3\pi s}}{s} + \frac{20e^{-4\pi s}}{s}$$

Step 2:- Take Laplace transform on both sides of the diff equation and substitute the value of $G(s)$ from step 1.

We have

$$(s^2 I(s) - sI(0) - I'(0)) + 2(sI(s) - I(0)) + 2I(s) = \frac{20}{s} - \frac{20e^{-3\pi s}}{s} + \frac{20e^{-4\pi s}}{s}$$

$$\text{where } I(s) = \mathcal{L}\{I(t)\}$$

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$$\therefore (s^2 + 2s + 2) I(s) = 10s + 20$$

$$= \frac{20}{s} - \frac{20e^{-3\pi s}}{s} + \frac{20e^{-4\pi s}}{s}$$

$$\therefore I(s) = \frac{10s + 20}{(s^2 + 2s + 2)} + \frac{20}{s((s+1)^2 + 1)} - \frac{20e^{-3\pi s}}{s((s+1)^2 + 1)} + \frac{20e^{-4\pi s}}{s((s+1)^2 + 1)}$$

Now $I(t) = \mathcal{L}^{-1} \{ I(s) \}$

$$= \mathcal{L}^{-1} \left\{ \frac{10s + 20}{s^2 + 2s + 2} \right\} + \mathcal{L}^{-1} \left\{ \frac{20}{((s+1)^2 + 1)} \right\} - \mathcal{L}^{-1} \left\{ \frac{20e^{-3\pi s}}{s((s+1)^2 + 1)} \right\} + \mathcal{L}^{-1} \left\{ \frac{20e^{-4\pi s}}{s((s+1)^2 + 1)} \right\}$$

Now

$$\mathcal{L}^{-1} \left\{ \frac{10s + 20}{((s+1)^2 + 1)} \right\} = \mathcal{L}^{-1} \left\{ \frac{10(s+1)}{((s+1)^2 + 1)} \right\} + \mathcal{L}^{-1} \left\{ \frac{10}{((s+1)^2 + 1)} \right\} = 10e^{-t} (\cos t + \sin t)$$

Consider

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$$\mathcal{L}^{-1} \left\{ \frac{20}{s(s+1)^2+1} \right\} = \mathcal{L}^{-1} \left\{ \frac{A}{s} + \frac{Bs+C}{(s+1)^2+1} \right\}$$

$$= \mathcal{L}^{-1} \left\{ \frac{A(s^2+2s+2) + Bs^2 + Cs}{s(s+1)^2+1} \right\}$$

$$= \mathcal{L}^{-1} \left\{ \frac{(A+B)s^2 + (2A+C)s + 2A}{s(s+1)^2+1} \right\}$$

$$\therefore 2A = 20$$
$$A = 10$$

$$A+B = 0$$

$$B = -A$$

$$B = -10$$

$$2A+C = 0$$

$$C = -2A$$

$$= -20$$

$$\therefore \mathcal{L}^{-1} \left\{ \frac{20}{s(s+1)^2+1} \right\} = \mathcal{L}^{-1} \left\{ \frac{10}{s} - \frac{10s}{(s+1)^2+1} - \frac{20}{(s+1)^2} \right\}$$

$$= \mathcal{L}^{-1} \left\{ \frac{10}{s} \right\} - \mathcal{L}^{-1} \left\{ \frac{10s+20}{(s+1)^2+1} \right\}$$

$$= 10 - 10e^{-t} (\cos t + \sin t)$$

Now

$$\mathcal{L}^{-1} \left\{ \frac{20e^{-3\pi s}}{s(s+1)^2+1} \right\} = (10 - 10e^{-(t-3\pi)}) (\cos(t-3\pi) + \sin(t-3\pi))$$

and

$$\mathcal{L}^{-1} \left\{ \frac{20e^{-4\pi s}}{s((s+1)^2+1)} \right\}$$

(10)

$$= (10 - 10e^{-(t-4\pi)}) (\cos(t-4\pi) + \sin(t-4\pi)) u(t-4\pi)$$

where we have used the fact that

$$\mathcal{L}^{-1} \{ e^{-as} F(s) \} = f(t-a) u(t-a)$$

where $\mathcal{L}^{-1} \{ F(s) \} = f(t)$

(Theorem 8 on page 387)

$$\therefore I(t)$$

$$= 10e^{-t} (\cos t + \sin t)$$

$$+ (10 - 10e^{-t} (\cos t + \sin t))$$

$$- (10 - 10e^{-(t-3\pi)} (\cos(t-3\pi) + \sin(t-3\pi))) u(t-3\pi)$$

$$+ (10 - 10e^{-(t-4\pi)} (\cos(t-4\pi) + \sin(t-4\pi))) u(t-4\pi)$$

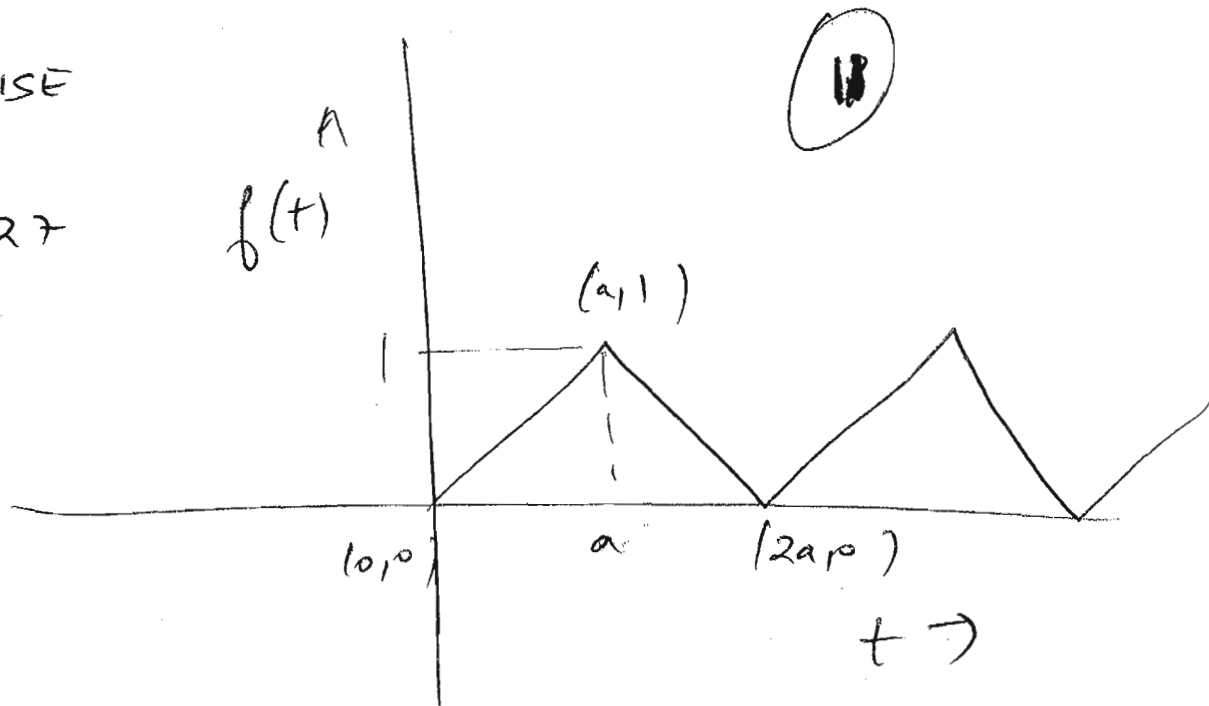
$$\therefore 10 - 10 u(t-3\pi) (1 + e^{-(t-3\pi)} (\cos t + \sin t))$$

$$+ 10 u(t-4\pi) (1 - e^{-(t-4\pi)} (\cos t + \sin t))$$

Since $\cos(t-3\pi) = -\cos t$, $\sin(t-3\pi) = -\sin t$

$\cos(t-4\pi) = \cos t$ and $\sin(t-4\pi) = \sin t$

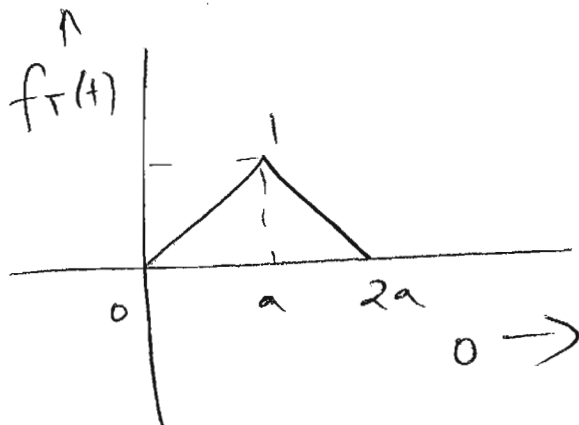
(3) EXERCISE
7.6
PROBLEM 27



Find the Laplace transform
of $f(t)$.

The period of $f(t)$ is $T = 2a$

Consider
 $f_T(t)$



$$\begin{aligned}
 f_T(t) &= \frac{t}{a}, \quad 0 < t < a \rightarrow \text{st line joining } (0,0) \text{ and } (a,1) \\
 &= -\frac{t}{a}(t-2a), \quad a < t < 2a \rightarrow \text{st line joining } (a,1) \text{ and } (2a,0) \\
 &= 0 \quad \text{otherwise}
 \end{aligned}$$

$$\therefore f_T(t) = \frac{t}{a}, \quad 0 < t < a \quad (12)$$

$$= \frac{-1}{a} (t-2a), \quad a < t < 2a$$

$$= 0 \quad \text{otherwise}$$

$$\therefore f_T(t) = \frac{t}{a} - \frac{2}{a} (t-a) u(t-a)$$

$$+ \frac{1}{a} (t-2a) u(t-2a)$$

(IN TERMS
OF UNIT STEP
functions).

Note that $f_T(t)$ is actually a continuous function and is also defined at $t=a, 2a$.

However, one can also write a CONTINUOUS function in terms of step functions.

$$\therefore F_T(s) = \mathcal{L} \left\{ f_T(t) \right\}$$

$$= \mathcal{L} \left\{ \frac{t}{a} - \frac{2}{a} (t-a) u(t-a) + \frac{1}{a} (t-2a) u(t-2a) \right\}$$

(13)

$$\therefore F_T(s)$$

$$= \mathcal{L} \left\{ \frac{t}{a} \right\} - \frac{2}{a} \mathcal{L} \left\{ (t-a) u(t-a) \right\} + \frac{1}{a} \mathcal{L} \left\{ (t-2a) u(t-2a) \right\}$$

Now $\mathcal{L} \left\{ f(t-a) u(t-a) \right\} = e^{-as} F(s)$
where $F(s) = \mathcal{L} \left\{ f(t) \right\}$
(see Theorem 8 on page 387)

$$\therefore F_T(s) = \frac{1}{as^2} - \frac{2}{a} e^{-as} \mathcal{L} \left\{ t \right\} + \frac{1}{a} e^{-2as} \mathcal{L} \left\{ t \right\}$$

$$= \frac{1}{as^2} - \frac{2}{a} \frac{e^{-as}}{s^2} + \frac{1}{a} \frac{e^{-2as}}{s^2}$$

$$= \frac{1}{as^2} (1 - 2e^{-as} + e^{-2as})$$

$$= \frac{1}{as^2} (1 - e^{-as})^2$$

$$\therefore F(s) = \frac{F_T(s)}{1 - e^{-sT}} = \frac{F_T(s)}{1 - e^{-2as}} = \frac{1}{as^2} \frac{(1 - e^{-as})^2}{(1 + e^{-as})(1 - e^{-as})}$$

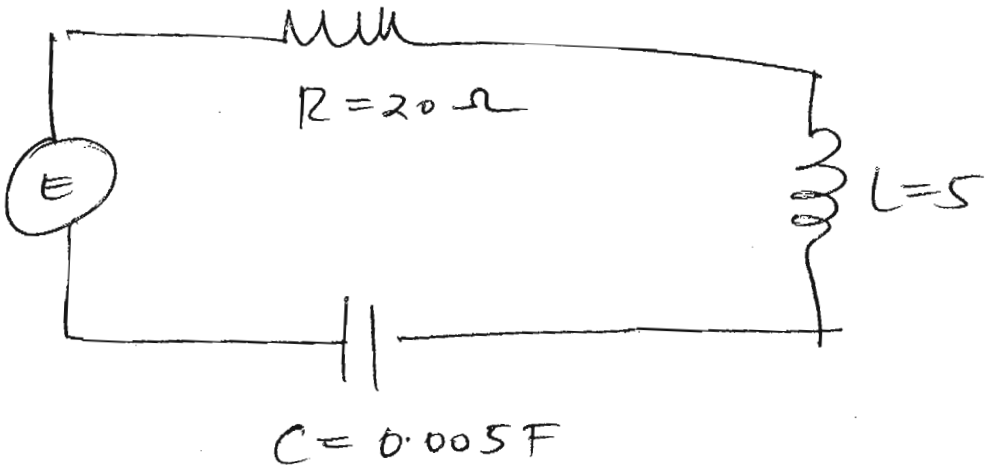
$$2. F(s) = \frac{1}{as^2} \frac{(1-e^{-as})}{(1+e^{-as})}$$

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EXERCISE

7.7, Problem
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$a = -1$ and $b = 8$

Consider

$$L I''(t) + R I'(t) + \frac{1}{C} I(t) = e(t)$$

$$I(0) = a, \quad I'(0) = b$$

$$\therefore 5 I''(t) + 20 I'(t) + 200 I(t) = e(t)$$

$$I(0) = -1, \quad I'(0) = 8$$

We will find $I(t)$ in two steps.

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(i) Step 1: - Find the impulse response $h(t)$ for the system

$$\text{where } h(s) = \mathcal{L}\{h(t)\} \\ = \frac{I(s)}{E(s)} \quad \text{where the initial conditions are assumed to be zero.}$$

In our case we have

$$5I''(t) + 20I'(t) + 200I(t) = e(t)$$

$$\therefore (5s^2 + 20s + 200)I(s) = E(s)$$

$$\therefore h(s) = \frac{1}{(5s^2 + 20s + 200)}$$

$$= \frac{1}{5(s^2 + 4s + 40)} = \frac{1}{5((s+2)^2 + 6^2)}$$

$$= \frac{1}{30} \frac{6}{(s+2)^2 + 6^2}$$

$$\therefore h(t) = \frac{1}{30} e^{-2t} \sin 6t$$

Step 2 :- Find the solution $I_k(t)$
to

$$5I''(t) + 20I'(t) + 200I(t) = 0$$

with $I(0) = -1$ and $I'(0) = 8$.

(18)

Char equation

$$u \quad \lambda^2 + 4\lambda + 40 = 0$$

$$\lambda = \frac{-4 \pm \sqrt{16 - 4(40)}}{2}$$

$$= \frac{-4 \pm \sqrt{-144}}{2}$$

$$= -2 \pm 6i$$

$$\alpha = -2$$

$$\beta = 6$$

$$\therefore I(t) = c_1 e^{-2t} \cos(6t) + c_2 e^{-2t} \sin(6t)$$

$$I'(t) = -2c_1 e^{-2t} \cos(6t) - 6c_1 e^{-2t} \sin(6t) \\ - 2c_2 e^{-2t} \sin(6t) + 6c_2 e^{-2t} \cos(6t)$$

$$I(0) = -1 \quad \text{gives} \quad \boxed{c_1 = -1}$$

$$I'(0) = -2c_1 + 6c_2 = 8$$

$$\therefore 2 + 6c_2 = 8 \quad \boxed{c_2 = 1}$$

$$\therefore I_k(t)$$

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$$= -e^{-2t} \cos(6t) + e^{-2t} \sin(6t)$$

By Theorem 12 on page 404
of the book we have

$$I(t) = (h * e)(t) \\ = -e^{-2t} \cos(6t) + e^{-2t} \sin(6t)$$

$$\therefore I(t) = \frac{1}{30} \int_0^t e^{-(t-\tau)} \cdot e^{-2\tau} \sin(6\tau) d\tau \\ = -e^{-2t} \cos(6t) + e^{-2t} \sin(6t)$$

(5)

EXERCISE 9.1

PROBLEM 13

$$x'' - 3x' + t^2 y - (\cos t)x = 0$$

$$y''' + y'' - tx' + y' + e^t x = 0$$

let $x_1 = x$

$$x_2 = x' = x_1'$$

$$x_3 = y$$

$$x_4 = y' = x_3'$$

$$x_5 = y'' = x_4'$$

The two diff equations
are

$$x_2' - 3x_2 + t^2 x_3 - (\cos t)x_1 =$$

$$x_5' + x_5 - tx_2 + x_4$$

$$+ e^t x_1 = 0$$

∴ we have

$$\begin{aligned}
 x_1' &= x_2 \\
 x_2' &= (\cos t)x_1 + 3x_2 - t^2x_3 \\
 x_3' &= x_4 \\
 x_4' &= x_5 \\
 x_5' &= -e^t x_1 + tx_2 - x_4 - x_5
 \end{aligned}$$

Let $X' = \begin{bmatrix} x_1' \\ x_2' \\ \vdots \\ x_5' \end{bmatrix}$ and $X = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_5 \end{bmatrix}$

$$\therefore X' = \begin{bmatrix} x_1' \\ x_2' \\ x_3' \\ x_4' \\ x_5' \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ (\cos t) & 3 & -t^2 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ -e^t & t & 0 & -1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix}$$

↑
A

∴ $X' = AX$

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EXERCISE 9.2

PROBLEM 13

Consider

$$2x_1 - 3x_2 = \lambda x_1$$

$$x_1 - 2x_2 = \lambda x_2$$

when
 $\lambda = 2$ and 1
respectively

Consider the case when

$$\lambda = 2 \text{ first}$$

$$2x_1 - 3x_2 = 2x_1$$

$$x_1 - 2x_2 = 2x_2$$

$$\therefore -3x_2 = 0$$
$$x_2 = 0$$

The 2nd equation

$$\text{gives } x_1 = 4x_2$$

$$\therefore x_1 = 0$$

\therefore The unique solution is $x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

Now consider the case when

$$\lambda = 1$$

$$\therefore 2x_1 - 3x_2 = x_1 \Rightarrow x_1 - 3x_2 = 0$$

$$x_1 - 2x_2 = x_2$$

$$x_1 - 3x_2 = 0$$

In reality there is only
one equation $x_1 - 3x_2 = 0$

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We have one degree of freedom here, i.e. we can choose any value for x_2 (for instance)

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however $x_1 = 3x_2$

∴ Any solution

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3x_2 \\ x_2 \end{bmatrix} = x_2 \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

For diff values of x_2 we obtain diff solutions

∴ In this case we have an infinite no of solutions

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EXERCISE 9.3
PROBLEM 30

Consider

$$A = \begin{bmatrix} 4 & -2 & 2 \\ -2 & 4 & 2 \\ 2 & 2 & 4 \end{bmatrix}$$

(a) Compute the inverse of A

2)

$$[A | I]$$

$$= \left[\begin{array}{ccc|ccc} 4 & -2 & 2 & 1 & 0 & 0 \\ -2 & 4 & 2 & 0 & 1 & 0 \\ 2 & 2 & 4 & 0 & 0 & 1 \end{array} \right]$$

$R_1 = \frac{1}{4} R_1$ ques

$$\rightarrow \left[\begin{array}{ccc|ccc} 1 & -1/2 & 1/2 & 1/4 & 0 & 0 \\ -2 & 4 & 2 & 0 & 1 & 0 \\ 2 & 2 & 4 & 0 & 0 & 1 \end{array} \right]$$

$R_2 = R_2 + 2R_1$ and $R_3 = R_3 - 2R_1$
ques

$$\rightarrow \left[\begin{array}{ccc|ccc} 1 & -1/2 & 1/2 & 1/4 & 0 & 0 \\ 0 & 3 & 3 & 1/2 & 1 & 0 \\ 0 & 3 & 3 & -1/2 & 0 & 1 \end{array} \right]$$

$R_2 = \frac{1}{3} R_2$ ques

$$\rightarrow \left[\begin{array}{ccc|ccc} 1 & -1/2 & 1/2 & 1/4 & 0 & 0 \\ 0 & 1 & 1 & 1/6 & 1/3 & 0 \\ 0 & 3 & 3 & -1/2 & 0 & 1 \end{array} \right]$$

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$$R_1 = R_1 + 1/2 R_2 \quad R_3 = R_3 - 3R_2 \quad \text{ques}$$

$$\rightarrow \left[\begin{array}{ccc|ccc} 1 & 0 & 1 & 1/3 & 1/6 & 0 \\ 0 & 1 & 1 & 1/6 & 1/3 & 0 \\ 0 & 0 & 0 & -1 & -1 & 1 \end{array} \right]$$

$$\frac{1}{4} \times 3 + \frac{4}{12}$$

We cannot proceed any further.
 Our eventual aim was to get the identity matrix I on the L.H.S.
 However we cannot get a 1 in pos (3,3) using elementary row operations.

∴ The row reduction procedure fails to produce the inverse of A .

$$(b) \det A$$

$$= 4(16-4) + 2(-8-4) \\ + 2(-4-8)$$

$$= 48 - 24 - 24 = 0$$

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(c) Find a nontrivial soln.
 x to $Ax = 0$.

$Ax = 0$ can be put in
the following form:

$$\left[\begin{array}{ccc|c} 4 & -2 & 2 & 0 \\ -2 & 4 & 2 & 0 \\ 2 & 2 & 4 & 0 \end{array} \right]$$

Using elementary row operations (as in part (a)),
this reduces to

$$\left[\begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

↳ Since the rhs is
zero it is unaffected
under the row operations performed.

∴ We have

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$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Note :- Performing the row operations both on the lhs, i.e. on the coefficient matrix, as well as the rhs leaves the solution x unchanged.

∴ We have

$$x_1 + x_3 = 0 \quad \Rightarrow \quad x_1 = -x_3$$

$$x_2 + x_3 = 0 \quad \Rightarrow \quad x_2 = -x_3$$

$$0 = 0$$

$$\therefore X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -x_3 \\ -x_3 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$$

Choosing $x_3 = 1$ gives
 $X = \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$

This is a non-trivial
soln to $AX = 0$.

(d) Note

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$$Ax = x_1 a_1 + x_2 a_2 + x_3 a_3$$

where a_1, a_2, a_3 are the
3 column vectors of A .

The desired scalars

c_1, c_2, c_3 all the coefficients

x_1, x_2, x_3 ^{computed} in part (c)

i.e. $c_1 = -1, c_2 = -1$ and $c_3 = 1$